

Automation1 XC2e

Compact PWM+ Drive

The Automation1 XC2e servo motor drive features PWM+ technology, delivering Aerotech's industry-leading linear amplifier performance in a compact, efficient PWM package. Improve motion quality with sub-nanometer in-position stability and boost throughput with fast step-and-settle and superior tracking performance in our smallest panel-mount drive.

Synchronize laser firing or process triggers with motion using multi-axis PSO, precisely align digital and analog I/O samples with the servo loop and prevent unexpected motion with safe torque off (STO).

Automation1

The XC2e is a part of the user-friendly Automation1 motion control platform, which includes the following:

- **Development Software**
- **Controls**
- **Motor Drives**
- Fiber-Optic HyperWire® Communication Bus

KEY FEATURES:

- Connects through the HyperWire® fiber-optic bus, which has 20 TIMES THE BANDWIDTH of 100BASE-T Ethernet buses
- Includes SAFE TORQUE OFF (STO) safety
- Generates 100 VDC BUS motor power & up to 10 AMPS PEAK output
- Features drive array with MORE THAN 67 MB of memory
- Collects analog sensor or position data **UP TO** 320 kHz (triggered by axis position)
- Offers many optional features, including Multiaxis Position Synchronized Output (PSO) & I/O expansion board

AUTOMATION1 XC2e GENERAL SPECIFICATIONS

CATEGORY	SPECIFICATION
Motor Style	Brush, brushless, voice coil, stepper ⁽¹⁾
Control Supply	24 VDC
Motor Supply	15-100 VDC
Bus Voltage ⁽²⁾	15-100 VDC
PWM Frequency	20 kHz
Peak Output Current (1 sec)(3)	10 A _{pk}
Continuous Output Current (3)	5 A
Position Synchronized Output (PSO)	Standard: One-axis PSO (includes one-axis part-speed PSO)* Optional: Two-axis PSO (includes two-axis part-speed PSO)* Two-axis part-speed PSO only* Three-axis part-speed PSO only* *Requires adding an expansion board to the drive to output PSO pulses via a physical connection.
25-Pin Motor Feedback Connector	High-speed differential inputs (encoder sin, cos and marker) CW and CCW limits Hall effect sensor inputs (A, B and C) Analog motor temperature input (accepts digital) Brake output
Multiplier Options	MX0 option: Primary encoder: 40 million counts per second square-wave input Auxiliary encoder: 40 million counts per second square-wave input MX2 option: Primary encoder: 2 MHz/450 kHz (bandwidth selectable) sine-wave input, encoder multiplier up to 65,536 Auxiliary encoder: 40 million counts per second square-wave input MX3 option: Primary encoder: 2 MHz/450 kHz (bandwidth selectable) sine-wave input, encoder multiplier up to 65,536 Auxiliary encoder: 450 kHz (bandwidth selectable) sine-wave input, encoder multiplier up to 65,536 Auxiliary encoder: 450 kHz sine-wave input, encoder multiplier up to x16,384* *Encoders multiplied with this input cannot be echoed out
I/O Expansion Board (-EB1)	PSO output connector with up to 12.5 MHz output rate Auxiliary Encoder Port 1x 16-bit differential, ±10 V analog input 1x 16-bit single-ended, ±10 V analog output 8x optically isolated digital inputs 8x optically isolated digital outputs



Chart continued on next page

AUTOMATION1 XC2e CONTROLLER SPECIFICATIONS

CATEGORY	SPECIFICATION
Drive Array Memory	67.1 MB (16,777,216 32-bit elements)
High Speed Data Capture	Yes (50 ns latency)
Safe Torque Off (STO)	Yes (SIL3/PLe/Cat 4)
HyperWire Connections	2x HyperWire small form-factor pluggable (SFP) ports
Automatic Brake Control	Standard (24 V at 0.5 A)
Absolute Encoder	Renishaw Resolute BiSS; EnDat 2.1; EnDat 2.2, and SSI
Current Loop Update Rate	20 kHz
Servo Loop Update Rate	20 kHz
Power Amplifier Bandwidth	2500 Hz maximum (software selectable)
Power Amplifier Efficiency	85-95% ⁽⁴⁾
Minimum Load Inductance	0.1 mH
Operating Temperature	0 to 40 °C
Storage Temperature	-30 to 85 °C
Weight	0.54 kg (1.20 lb.)
Compliance	CE approved, NRTL safety certification, EU 2015/863 RoHS 3 directive

^{1.} For stepper motors only, one-half of bus voltage is applied across the motor (e.g., 80 VDC supply results in 40 VDC across stepper motor).

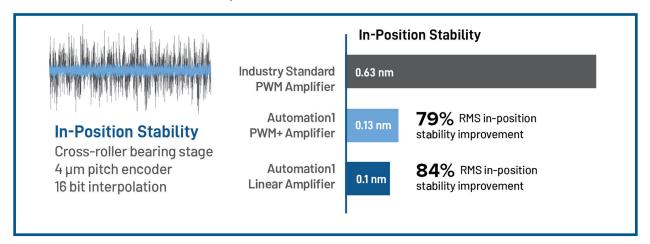
- 2. Output voltage dependent upon input voltage.
- 3. Peak value of the sine wave; RMS current for AC motors is 0.707 $A_{\rm pk}$.
- 4. Dependent on total output power: efficiency increases with increasing output power.



AUTOMATION1 XC2e ORDERING OPTIONS

Automation1-XC2e	Automation1-XC2e - Enhanced, Compact PWM Servo Drive
Peak Current	
-10	10 A peak, 5 A cont. current (default)
Amplifier Type	
-PWM+	With PWM+ amplifier
Expansion Board	
-EB0	No expansion board (default)
-EB1	IO expansion board
Multiplier	
-MX0	No encoder multiplier (default)
-MX2	x65536 multiplier (primary), no multiplier (auxiliary)
-MX3	x65536 multiplier (primary), x16384 multiplier (auxiliary)
PSO ⁽¹⁾	
-PSO1	One-axis PSO (includes one-axis part-speed PSO) (default)
-PSO2	Two-axis PSO (includes three-axis part-speed PSO)
-PSO5	Two-axis part-speed PSO
-PSO6	Three-axis part-speed PSO
-PSO1 -PSO2 -PSO5	Two-axis PSO (includes three-axis part-speed PSO) Two-axis part-speed PSO

AUTOMATION1 PWM+, LINEAR AMPLIFIER PERFORMANCE IN A PWM PACKAGE





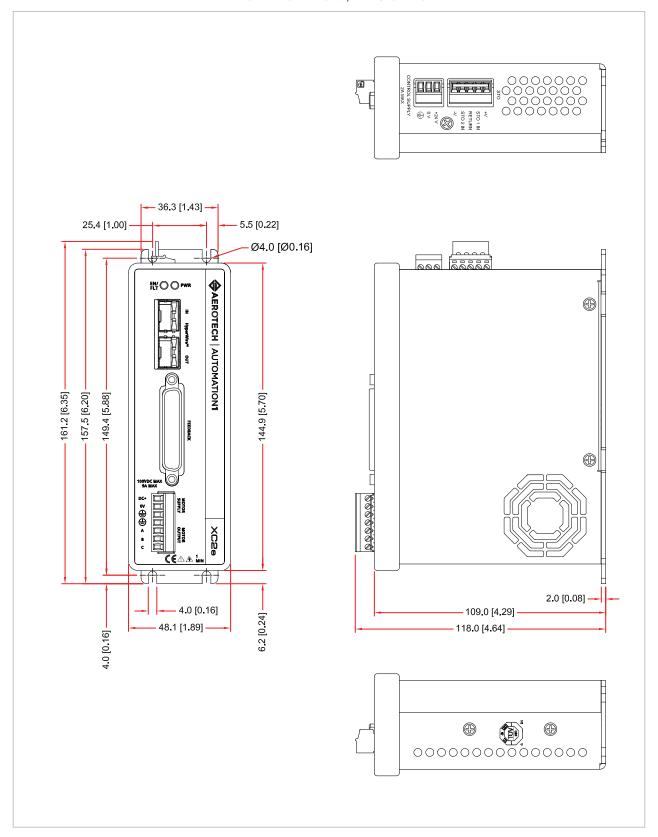
AUTOMATION1 PS2 DIN RAIL POWER SUPPLY ORDERING OPTIONS

Automation1 PS2	Automation1-PS2 - Din-rail mounted power supply for 1 to 4 compact servo drives
Drive Type (Require	d)
-D1	PS2 for XC2, XC2e drives and iXC2e & iXC2 drive-based controllers
-D2	PS2 for XL2e drives and iXL2e drive-based controllers
Power Output (Requ	uired)
-P1	240 watts at 24 VDC
-P2	240 watts at 48 VDC
-P3	480 watts at 48 VDC
-P4	480 watts at 96 VDC
-P5	240 watts at +/-12 VDC (10A)
-P6	240 watts at +/-24 VDC (5A)
-P7	480 watts at +/-48 VDC (5A)
Number of Axes (Re	equired)
-AX01	1 axis of wiring
-AX02	2 axes of wiring
-AX03	3 axes of wiring
-AX04	4 axes of wiring



AUTOMATION1 XC2e DIMENSIONS

AUTOMATION1 XC2e, -EB0 OPTION





AUTOMATION1 XC2e DIMENSIONS

AUTOMATION1 XC2e, -EB1 OPTION

