# Npag<sup>®</sup> MR Series

# **Drive Racks**

3U, 19-inch rack-mount design with integral drives

Flexible design provides the ability to drive brush, brushless, or stepper motors with the same amplifier

5 A continuous, 10 amp peak output current

PWM or linear amplifiers

**Integral power supplies** 

**IEEE-1394 FireWire® interface** 

Digital current, velocity, and position loops for improved motion stability

Optional Ethernet for I/O expansion

Integrated encoder multiplier for higher throughput and reduced wiring

**CE** approved and NRTL safety certification; follows the 2011/65/EU RoHS 2 Directive

The Npaq® MR is a cost-effective, high performance, 4- or 8-axis drive rack. All versions are 3U in size, rackmountable, and compatible with the Automation 3200 motion platform.

Featuring high-performance double-precision DSPs, the Npaq MR family performs both current loop and servoloop closures digitally to ensure the highest level of positioning accuracy and rate stability. It is this processing capability that allows the Npaq MR to provide loop closure rates up to 20 kHz and to handle both digital and analog I/O processing, data collection, laser firing, and encoder multiplication tasks in real time.



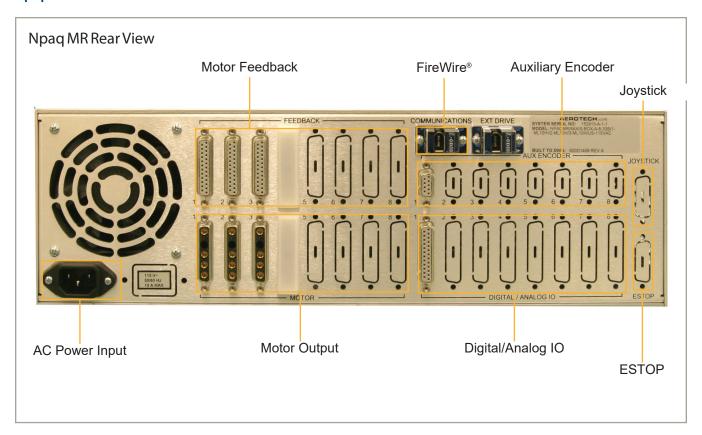


Standard options for the Npaq MR include integrated encoder multiplication, per axis brake control logic, I/O expansion, and integrated emergency stop circuitry.

The Npaq MR uses integral amplifiers supporting both linear and PWM topologies to control brushless, DC brush, or stepper motor types. The Npaq MR supports one integrated motor operation voltage with mains turn-on current limiting.

The Npaq MR supports single-axis position synchronized output (PSO) for precise synchronizing of external devices, and supports per axis I/O options with up to 64 optoisolated inputs and outputs available to the user.

## Npaq® MR Series COMPONENTS



Integrated Amplifier Electrical	Specifications	MP	ML	
Output Voltage	VDC	10, 20, 30, 40, 80	10, 20, 30, 40	
Peak Output Current	A	10	10 <sup>(1)</sup>	
Continuous Output Current	A	5	5 <sup>(1)</sup>	
PWM Switching Frequency	kHz	20	N/A	
Power Amplifier Bandwidth	kHz	Software Selectable	Software Selectable	
Minimum Load Inductance	mH	0.1	0	
Operating Temperature	°C	0 to 50	0 to 50	
Storage Temperature	°C	-20 to 85	-20 to 85	
Weight	kg	0.5	0.5	

Notes:

<sup>1.</sup> Actual current ratings dependent on motor resistance.

# Npaq® MR Series SPECIFICATIONS

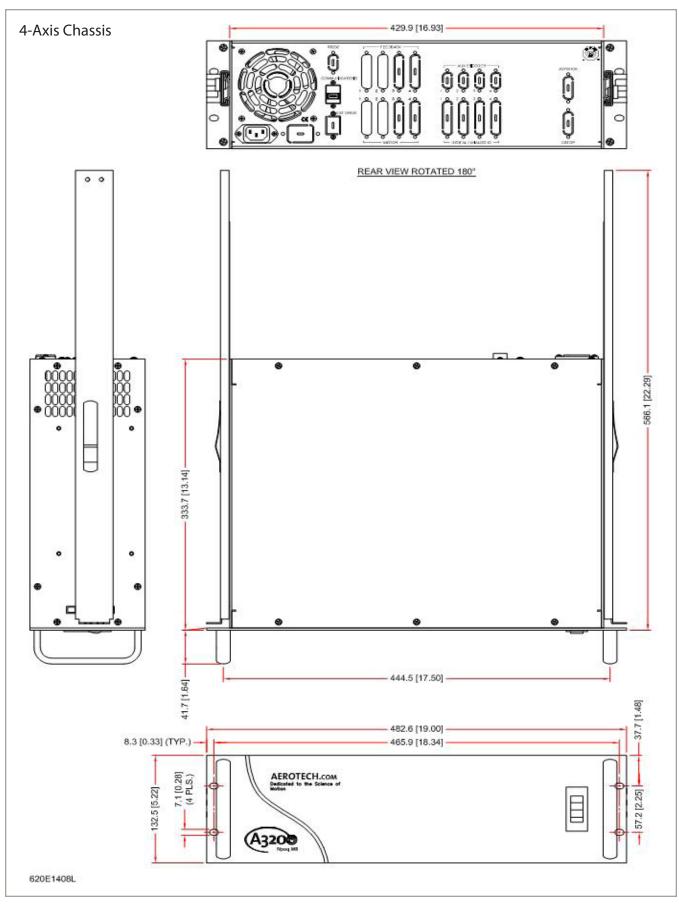
Number of Axes	
Motor Style   Brush, Brushless, Stepper	
Power Supply	
Bus Voltage VDC 10-80 Peak Output Current (1 sec) <sub>(1)</sub> A <sub>ja</sub> 10 Continuous Output Current <sub>(1)</sub> A <sub>ja</sub> 5 Digital Inputs Optional <sub>(2)</sub> Digital Outputs Optional <sub>(3)</sub> Analog Inputs Optional <sub>(3)</sub> Analog Inputs Optional <sub>(3)</sub> Dedicated Axis I/O on Feedback Connector  Three Limit Inputs (CW, CCW, Home); Three Hall Effect Inputs (A, B, C); Three High-Differential Inputs (Sin, cos, mkr for encoder); Motor Over-Temperature Input Dedicated I/O on Auxiliary Feedback Connector  I/O Expansion Board <sub>(3)</sub> One 12-bit Differential Analog Input; One 16-bit Analog Output; Eight Digital Inputs, O Isolated, Sinking or Sourcing; Eight Optically-Isolated Digital Outputs per Axis High Speed Data Capture  High Speed Digital Outputs No Bi-Directional Lines No Automatic Brake Control Desition Synchronized Output (PSO) Single Axis Standard Can Output Multiplied Encoder Can Output Multiplied Encoder Primary Encoder Input Frequency with Multiplication Primary Encoder Input Frequency - Square Wave Secondary Encoder Input Frequency - Square Wave Secondary Encoder Input Frequency - Square Wave Laser Feedback Support No Internal Shunt Resistor No Internal Shunt Resistor	
Peak Output Current (1 sec) <sub>100</sub> A <sub>14</sub> 10  Continuous Output Current <sub>(10)</sub> A <sub>14</sub> 5  Digital Inputs Optional <sub>100</sub> Digital Outputs Optional <sub>100</sub> Digital Outputs Optional <sub>100</sub> Analog Inputs Optional <sub>100</sub> Analog Outputs Optional <sub>100</sub> Dedicated Axis I/O on Feedback Connector Three Limit Inputs (CW, CCW, Home); Three Hall Effect Inputs (A, B, C); Three High-Differential Inputs (sin, cos, mkr for encoder); Motor Over-Temperature Input Optional Optiona	
Continuous Output Curren <sub>(1)</sub> A <sub>x</sub> 5 Digital Inputs Optional <sub>(2)</sub> Digital Outputs Optional <sub>(3)</sub> Analog Inputs One 12-bit Differential Per Axis Analog Outputs Optional <sub>(3)</sub> Dedicated Axis I/O on Feedback Connector Dedicated Axis I/O on Auxiliary Feedback Connector  Three Limit Inputs (CW, CCW, Home); Three Hall Effect Inputs (A, B, C); Three High-Differential Inputs (sin, cos, mkr for encoder); Motor Over-Temperature Input I/O Expansion Board <sub>(3)</sub> One 12-bit Differential Analog Input, One 16-bit Analog Output; Eight Digital Inputs, O Isolated, Sinking or Sourcing; Eight Optically-Isolated Digital Outputs per Axis High Speed Digital Outputs No Bi-Directional Lines No Bi-Directional Lines No Automatic Brake Control Optional Emergency Stop (ESTOP) Optional  Emergency Stop (ESTOP) Single Axis Standard Can Output Multiplied Encoder Only With MXH Option Can Output Multiplied Encoder Only With MXH Option Primary Encoder Input Frequency with Multiplication 200 kHz sine wave (MXU); 450 kHz sine wave (MXH) Primary Encoder Input Frequency — Square Wave 10 MHz square wave frequency/40 MHz count rate Secondary Encoder Input Frequency 10 MHz square wave frequency/40 MHz count rate Laser Feedback Support No Internal Shunt Resistor No	
Continuous Output Current	
Digital Inputs   Optional <sub>c</sub> ;   One 12-bit Differential Per Axis   One 12-bit Differential Inputs (CW, CCW, Home); Three Hall Effect Inputs (A, B, C); Three High-Differential Inputs (sin, cos, mkr for encoder); Motor Over-Temperature Input   One 12-bit Differential Inputs (sin, cos, mkr for encoder); Motor Over-Temperature Input   I/O Expansion Board <sub>cs</sub>   One 12-bit Differential Analog Input; One 16-bit Analog Output; Eight Digital Inputs, One 12-bit Differential Analog Input; One 16-bit Analog Output; Eight Digital Inputs, One 12-bit Differential Analog Input; One 16-bit Analog Output; Eight Digital Inputs, One 12-bit Differential Analog Input; One 16-bit Analog Output; Press   Noe   Isolated, Sinking or Sourcing; Eight Optically-Isolated Digital Outputs per Axis   Noe   No	
Analog Inputs One 12-bit Differential Per Axis Analog Outputs Dedicated Axis I/O on Feedback Connector Three Limit Inputs (CW, CCW, Home); Three Hall Effect Inputs (A, B, C); Three High-Differential Inputs (sin, cos, mkr for encoder); Motor Over-Temperature Input Dedicated I/O on Auxiliary Feedback Connector I/O Expansion Board <sub>co</sub> One 12-bit Differential Inputs (sin, cos, mkr for encoder); Motor Over-Temperature Input I/O Expansion Board <sub>co</sub> One 12-bit Differential Analog Input; One 16-bit Analog Output; Eight Digital Inputs, O Isolated, Sinking or Sourcing; Eight Optically-Isolated Digital Outputs per Axis High Speed Data Capture Yes High Speed Digital Outputs No Bi-Directional Lines No Automatic Brake Control Optional Emergency Stop (ESTOP) Optional Position Synchronized Output (PSO) Single Axis Standard Can Output Multiplied Encoder Only With MXH Option Can Output Square Wave Encoder Yes Primary Encoder Input Frequency with Multiplication Primary Encoder Input Frequency — Square Wave 10 MHz square wave frequency/40 MHz count rate Secondary Encoder Input Frequency 10 MHz square wave frequency/40 MHz count rate Secondary Encoder Input Frequency No Encoder Multiplication <sub>(0)</sub> X4096 (MXU); x65536 (MXH) Resolver/Inductosyn Interface No Internal Shunt Resistor	
Analog Outputs  Dedicated Axis I/O on Feedback Connector  Dedicated I/O on Auxiliary Feedback Connector  Dedicated I/O on Auxiliary Feedback Connector  Dedicated I/O on Auxiliary Feedback Connector  I/O Expansion Board <sub>(2)</sub> One 12-bit Differential Analog Input; One 16-bit Analog Output; Eight Digital Inputs, O Isolated, Sinking or Sourcing; Eight Optically-Isolated Digital Outputs per Axis  High Speed Data Capture  High Speed Digital Outputs  No  Bi-Directional Lines  No  Automatic Brake Control  Desition Synchronized Output (PSO)  Can Output Multiplied Encoder  Can Output Multiplied Encoder  Can Output Square Wave Encoder  Primary Encoder Input Frequency with Multiplication  Primary Encoder Input Frequency  10 MHz square wave frequency/40 MHz count rate  Secondary Encoder Input Frequency  10 MHz square wave frequency/40 MHz count rate  Laser Feedback Support  No  Internal Shunt Resistor  No	
Dedicated Axis I/O on Feedback Connector	
Dedicated I/O on Auxiliary Feedback Connector  Differential Inputs (sin, cos, mkr for encoder); Motor Over-Temperature Input I/O Expansion Board <sub>(2)</sub> Done 12-bit Differential Analog Input; One 16-bit Analog Output; Eight Digital Inputs, O Isolated, Sinking or Sourcing; Eight Optically-Isolated Digital Outputs per Axis High Speed Data Capture  High Speed Digital Outputs  No  Bi-Directional Lines  No  Automatic Brake Control  Emergency Stop (ESTOP)  Position Synchronized Output (PSO)  Can Output Multiplied Encoder  Can Output Multiplied Encoder  Primary Encoder Input Frequency with Multiplication  Primary Encoder Input Frequency with Multiplication  Primary Encoder Input Frequency — Square Wave  Secondary Encoder Input Frequency  10 MHz square wave frequency/40 MHz count rate  Secondary Encoder Input Frequency  10 MHz square wave frequency/40 MHz count rate  Laser Feedback Support  No  Internal Shunt Resistor  No	
I/O Expansion Board <sub>in</sub> One 12-bit Differential Analog Input; One 16-bit Analog Output; Eight Digital Inputs, O Isolated, Sinking or Sourcing; Eight Optically-Isolated Digital Outputs per Axis  High Speed Data Capture  High Speed Digital Outputs  No  Bi-Directional Lines  No  Automatic Brake Control  Emergency Stop (ESTOP)  Optional  Emergency Stop (ESTOP)  Position Synchronized Output (PSO)  Can Output Multiplied Encoder  Can Output Square Wave Encoder  Primary Encoder Input Frequency with Multiplication  Primary Encoder Input Frequency — Square Wave  Secondary Encoder Input Frequency  10 MHz square wave frequency/40 MHz count rate  Secondary Encoder Input Frequency  10 MHz square wave frequency/40 MHz count rate  No  Encoder Multiplication <sub>(D)</sub> Encoder Multiplication <sub>(D)</sub> Resolver/Inductosyn Interface  No  Internal Shunt Resistor	
Isolated, Sinking or Sourcing; Eight Optically-Isolated Digital Outputs per Axis  High Speed Data Capture  High Speed Digital Outputs  No  Bi-Directional Lines  No  Automatic Brake Control  Emergency Stop (ESTOP)  Position Synchronized Output (PSO)  Can Output Multiplied Encoder  Can Output Multiplied Encoder  Can Output Square Wave Encoder  Primary Encoder Input Frequency with Multiplication  Primary Encoder Input Frequency — Square Wave  Secondary Encoder Input Frequency  Laser Feedback Support  Encoder Multiplication  Encoder Multiplication  No  Internal Shunt Resistor  No	
High Speed Digital Outputs  Bi-Directional Lines  No  Automatic Brake Control  Coptional  Emergency Stop (ESTOP)  Position Synchronized Output (PSO)  Can Output Multiplied Encoder  Can Output Square Wave Encoder  Primary Encoder Input Frequency with Multiplication  Primary Encoder Input Frequency — Square Wave  Secondary Encoder Input Frequency  10 MHz square wave frequency/40 MHz count rate  Secondary Encoder Input Frequency  10 MHz square wave frequency/40 MHz count rate  Laser Feedback Support  No  Encoder Multiplication  Resolver/Inductosyn Interface  No  Internal Shunt Resistor	
Bi-Directional Lines  Automatic Brake Control  Emergency Stop (ESTOP)  Optional  Position Synchronized Output (PSO)  Can Output Multiplied Encoder  Can Output Square Wave Encoder  Primary Encoder Input Frequency with Multiplication  Primary Encoder Input Frequency — Square Wave  Secondary Encoder Input Frequency  10 MHz square wave frequency/40 MHz count rate  Secondary Encoder Input Frequency  10 MHz square wave frequency/40 MHz count rate  Laser Feedback Support  No  Encoder Multiplication(s)  Resolver/Inductosyn Interface  No  Internal Shunt Resistor	
Automatic Brake Control  Emergency Stop (ESTOP)  Optional  Position Synchronized Output (PSO)  Can Output Multiplied Encoder  Can Output Square Wave Encoder  Primary Encoder Input Frequency with Multiplication  Primary Encoder Input Frequency — Square Wave  Secondary Encoder Input Frequency  10 MHz square wave frequency/40 MHz count rate  Secondary Encoder Input Frequency  Laser Feedback Support  No  Encoder Multiplication  Resolver/Inductosyn Interface  No  Internal Shunt Resistor  Optional	
Emergency Stop (ESTOP)  Position Synchronized Output (PSO)  Single Axis Standard  Can Output Multiplied Encoder  Can Output Square Wave Encoder  Primary Encoder Input Frequency with Multiplication  Primary Encoder Input Frequency – Square Wave  Secondary Encoder Input Frequency  10 MHz square wave frequency/40 MHz count rate  Secondary Encoder Input Frequency  10 MHz square wave frequency/40 MHz count rate  Laser Feedback Support  No  Encoder Multiplication <sub>(3)</sub> Resolver/Inductosyn Interface  No  Internal Shunt Resistor  No	
Position Synchronized Output (PSO)  Can Output Multiplied Encoder  Can Output Square Wave Encoder  Primary Encoder Input Frequency with Multiplication  Primary Encoder Input Frequency — Square Wave  Secondary Encoder Input Frequency  10 MHz square wave frequency/40 MHz count rate  Secondary Encoder Input Frequency  10 MHz square wave frequency/40 MHz count rate  Laser Feedback Support  No  Encoder Multiplication(3)  Resolver/Inductosyn Interface  No  Internal Shunt Resistor  No	
Can Output Multiplied Encoder  Can Output Square Wave Encoder  Primary Encoder Input Frequency with Multiplication  Primary Encoder Input Frequency – Square Wave  Secondary Encoder Input Frequency  10 MHz square wave frequency/40 MHz count rate  10 MHz square wave frequency/40 MHz count rate  No  Encoder Multiplication <sub>(3)</sub> Resolver/Inductosyn Interface  No  Internal Shunt Resistor  No  Only With MXH Option  Yes  100 KHz sine wave (MXH)  10 MHz square wave frequency/40 MHz count rate  10 MHz square wave frequency/40 MHz count rate  No  No  Internal Shunt Resistor	
Can Output Square Wave Encoder  Primary Encoder Input Frequency with Multiplication  200 kHz sine wave (MXU); 450 kHz sine wave (MXH)  Primary Encoder Input Frequency – Square Wave  10 MHz square wave frequency/40 MHz count rate  Secondary Encoder Input Frequency  10 MHz square wave frequency/40 MHz count rate  No  Encoder Multiplication <sub>(3)</sub> Resolver/Inductosyn Interface  No  Internal Shunt Resistor  No	
Primary Encoder Input Frequency with Multiplication  200 kHz sine wave (MXU); 450 kHz sine wave (MXH)  Primary Encoder Input Frequency – Square Wave  Secondary Encoder Input Frequency  10 MHz square wave frequency/40 MHz count rate  Laser Feedback Support  No  Encoder Multiplication <sub>(3)</sub> Resolver/Inductosyn Interface  No  Internal Shunt Resistor  No	
Primary Encoder Input Frequency – Square Wave  Secondary Encoder Input Frequency  10 MHz square wave frequency/40 MHz count rate  10 MHz square wave frequency/40 MHz count rate  10 MHz square wave frequency/40 MHz count rate  No  Encoder Multiplication(s)  Resolver/Inductosyn Interface  No  Internal Shunt Resistor  No	
Secondary Encoder Input Frequency  Laser Feedback Support  Encoder Multiplication <sub>(3)</sub> Resolver/Inductosyn Interface  Internal Shunt Resistor  10 MHz square wave frequency/40 MHz count rate  No  No  No	
Laser Feedback Support  Encoder Multiplication <sub>(3)</sub> Resolver/Inductosyn Interface  Internal Shunt Resistor  No  No	
Encoder Multiplication <sub>(3)</sub> x4096 (MXU); x65536 (MXH)  Resolver/Inductosyn Interface No  Internal Shunt Resistor No	
Resolver/Inductosyn Interface No Internal Shunt Resistor No	
Internal Shunt Resistor No	
External Shunt No	
<b>Ethernet</b> No	
USB No	
<b>RS-232 No</b> No	
FireWire Yes	
Fieldbus Modbus TCP on PC	
Joystick Support Yes	
Current Loop Update Rate kHz 20	
Servo Loop Update Rate	
Power Amplifier Bandwidth         kHz         Selectable Through Software	
Minimum Load Inductance         mH         0.1 mH with PWM; 0 With Linear	
Operating Temperature °C 0 to 50	
Storage Temperature °C -30 to 85	
Weight         kg (lb)         16 (35)	
Package Amplifiers Installed at Factory	
Standards         CE approved, NRTL safety certification, EU 2015/863 RoHS 3 directive	

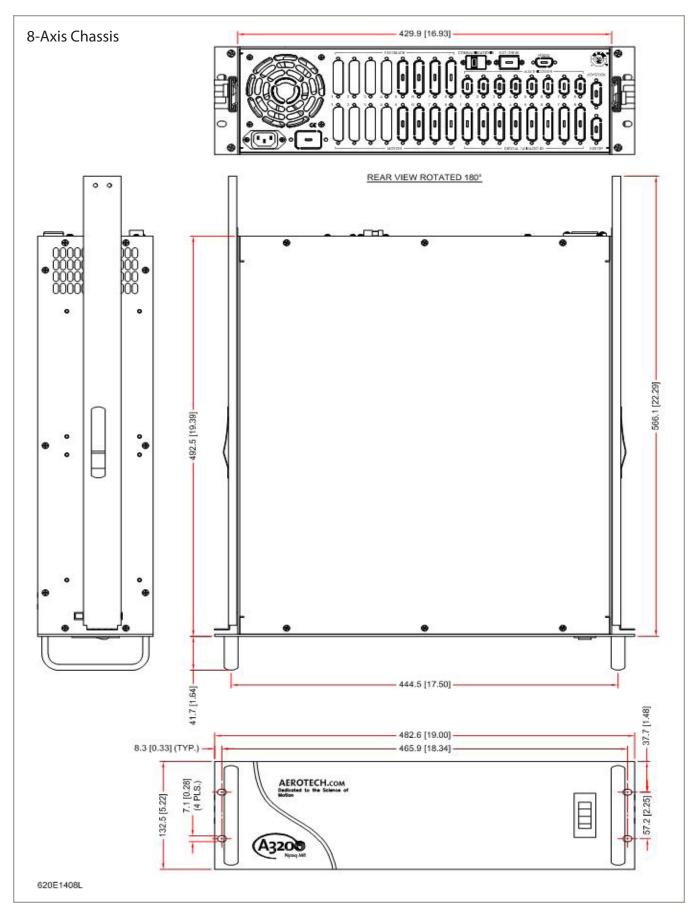
Notes:

1. Peak value of the sine wave; rms current for AC motors is 0.707 \* Apx.

2. Requires I/O option.

3. Effective resolution after quadrature decoding if applicable.





#### **Ordering Example**

Npaq MR	/4AXIS-BOX	-A	-4-40LP	/1-MP10I	/2-MP10	/3-MP10
Base	Package	Line Voltage	Bus Power Supply	Axis 1 Amp	Axis 2 Amp	Axis 3 Amp
	/4AXIS-BOX /8AXIS-BOX	-A -B -C -D	-4-40LP -4-80LP -4-40 -4-80 -4-10B -4-20B -4-30B -4-40B -8-40LP -8-80LP -8-80 -8-10B -8-20B -8-20B -8-30B	/1-MP10 /1-MP10I /1-MP10MI /1-MP10-HB /1-MP10-HB /1-MP10H-HB /1-MP10M-HB /1-ML10 /1-ML10I /1-ML10I /1-ML10HI	/2-MP10 /2-MP10I /2-MP10MI /2-MP10MI /2-MP10-HB /2-MP10I-HB /2-MP10MI-HB /2-MP10MI-HB /2-ML10 /2-ML10I /2-ML10HI /2-ML10HI	/3-MP10 /3-MP10I /3-MP10MI /3-MP10MI /3-MP10-HB /3-MP10I-HB /3-MP10MI-HB /3-ML10I /3-ML10I /3-ML10MI /3-ML10MI /3-ML10HI

#### **Ordering Example (continued)**

/4-MP10	/5-MP10	/6-MP10	/7-MP10	/8-MP10	/US-115VAC	/Brake-2
Axis 4 Amp	Axis 5 Amp	Axis 6 Amp	Axis 7 Amp	Axis 8 Amp	Line Cord	Brake Options
/4-MP10 /4-MP10I /4-MP10MI /4-MP10-HB /4-MP10I-HB /4-MP10MI-HB /4-MP10MI-HB /4-ML10 /4-ML10I /4-ML10I /4-ML10MI /4-ML10HI	/5-MP10 /5-MP10I /5-MP10M /5-MP10HB /5-MP10-HB /5-MP10I-HB /5-MP10M-HB /5-MP10MI-HB	/6-MP10 /6-MP10I /6-MP10M /6-MP10HI /6-MP10-HB /6-MP10I-HB /6-MP10M-HB /6-MP10MI-HB	/7-MP10 /7-MP10I /7-MP10M /7-MP10MI /7-MP10-HB /7-MP10I-HB /7-MP10M-HB /7-MP10MI-HB	/8-MP10 /8-MP10I /8-MP10M /8-MP10MI /8-MP10-HB /8-MP10I-HB /8-MP10M-HB /8-MP10MI-HB	/ENGLAND /GERMANY /ISRAEL /INDIA /AUSTRALIA /US-115VAC /US-230VAC /NO-LINECORD	/Brake-1 /Brake-2 /Brake-3 /Brake-4 /Brake-5 /Brake-6 /Brake-7 /Brake-8

#### Npaq MR

Rack-mount digital amplifier chassis with integral DC power supply and FireWire® interface. Npaq MR Supports 4 or 8 axes of brush, brushless, or stepper motor amplifiers.

-Dedicated I/O per axis includes: CW, CCW, and home limits, sin, cos, mkr, Hall effect sensors,

motor over-temperature, ext fault

-User defined I/O included on I/O option board: 8 opto-isolated inputs (sinking or sourcing), 8 outputs (sinking or sourcing), one 12-bit analog input, one 16-bit analog output and brake relay

#### **Package**

/4AXIS-BOX	Supports up to 4 axes of motion
/8AXIS-BOX	Supports up to 8 axes of motion

#### Line Voltage

-A	115 VAC line
-B	230 VAC line
-C	100 VAC line
-D	200 VAC line

#### **Bus Power Supply**

-4-40LP -4-80LP -4-40 -4-80	Four-axis rack with 40 VDC bus; up to 300 watts Four-axis rack with 80 VDC bus; up to 300 watts Four-axis rack with 40 VDC bus; up to 600 watts Four-axis rack with 80 VDC bus; up to 600 watts
-4-10B -4-20B	Four-axis rack with ±10 VDC bus; up to 400 watts
-4-20B -4-30B	Four-axis rack with ±20 VDC bus; up to 400 watts Four-axis rack with ±30 VDC bus; up to 400 watts
-4-40B	Four-axis rack with ±40 VDC bus; up to 400 watts
-8-40LP	Eight-axis rack with 40 VDC bus; up to 500 watts
-8-80LP	Eight-axis rack with 80 VDC bus; up to 500 watts
-8-40	Eight-axis rack with 40 VDC bus; up to 500 watts
-8-80	Eight-axis rack with 80 VDC bus; up to 1000 watts
-8-10B	Eight-axis rack with $\pm 10$ VDC bus; up to 400 watts
-8-20B	Eight-axis rack with ±20 VDC bus; up to 400 watts
-8-30B	Eight-axis rack with $\pm 30$ VDC bus; up to 400 watts
-8-40B	Eight-axis rack with ±40 VDC bus; up to 600 watts

#### **Axis 1 Amplifier Options**

Total Extendition operans	
/1-MP10	Digital PWM amplifier, 10 A peak, 5 A continuous
/1-MP10I	Digital PWM amplifier, 10 A peak, 5 A continuous with I/O option
/1-MP10M	Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU <sup>(1)</sup>
/1-MP10MI	Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU <sup>(1)</sup> and I/O option
/1-MP10-HB	Digital PWM amplifier, 10 A peak, 5 A continuous with half bus option
/1-MP10I-HB	Digital PWM amplifier, 10 A peak, 5 A continuous with I/O and half bus option
/1-MP10M-HB	Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU(1) and half bus option
/1-MP10MI-HB	Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU <sup>(1)</sup> with I/O and half bus option
/1-ML10	Linear amplifier, 10 A peak, 5 A continuous
/1-ML10I	Linear amplifier, 10 A peak, 5 A continuous with I/O option
/1-ML10M	Linear amplifier, 10 A peak, 5 A continuous; x4096 MXU <sup>(1)</sup>
/1-ML10MI	Linear amplifier, 10 A peak, 5 A continuous; x4096 MXU <sup>(1)</sup> with I/O option
/1-ML10H	Digital linear amplifier, 10 A peak, 5 A continuous; x65536 MXH <sup>(1)</sup>
/1-ML10HI	Digital linear amplifier, 10 A peak, 5 A continuous; x65536 MXH(1) with I/O option
Note:	

<sup>1.</sup> Effective multiplication factor specified after quadrature decoding (if applicable).

#### **Axis 2 Amplifier Options**

/2-MP10	Digital PWM amplifier, 10 A peak, 5 A continuous
/2-MP10I	Digital PWM amplifier, 10 A peak, 5 A continuous with I/O option
/2-MP10M	Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU <sup>(1)</sup>
/2-MP10MI	Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU <sup>(1)</sup> and I/O option
/2-MP10-HB	Digital PWM amplifier, 10 A peak, 5 A continuous with half bus option
/2-MP10I-HB	Digital PWM amplifier, 10 A peak, 5 A continuous with I/O and half bus option
/2-MP10M-HB	Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU(1) and half bus option
/2-MP10MI-HB	Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU(1) with I/O and half bus option
/2-ML10	Linear amplifier, 10 A peak, 5 A continuous
/2-ML10I	Linear amplifier, 10 A peak, 5 A continuous with I/O option
/2-ML10M	Linear amplifier, 10 A peak, 5 A continuous; x4096 MXU <sup>(1)</sup>
/2-ML10MI	Linear amplifier, 10 A peak, 5 A continuous; x4096 MXU <sup>(1)</sup> with I/O option
/2-ML10H	Digital linear amplifier, 10 A peak, 5 A continuous; x65536 MXH <sup>(1)</sup>
/2-ML10HI	Digital linear amplifier, 10 A peak, 5 A continuous; x65536 MXH <sup>(1)</sup> with I/O option
Note:	

<sup>1.</sup> Effective multiplication factor specified after quadrature decoding (if applicable).

#### **Axis 3 Amplifier Options**

/3-MP10	Digital PWM amplifier, 10 A peak, 5 A continuous
/3-MP10I	Digital PWM amplifier, 10 A peak, 5 A continuous with I/O option
/3-MP10M	Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU <sup>(1)</sup>

/3-MP10MI Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU<sup>(1)</sup> and I/O option /3-MP10-HB Digital PWM amplifier, 10 A peak, 5 A continuous with half bus option /3-MP10I-HB Digital PWM amplifier, 10 A peak, 5 A continuous with I/O and half bus option /3-MP10M-HB Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU<sup>(1)</sup> and half bus option /3-MP10MI-HB Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU(1) with I/O and half bus option

/3-ML10 Linear amplifier, 10 A peak, 5 A continuous

Linear amplifier, 10 A peak, 5 A continuous with I/O option /3-ML10I /3-ML10M Linear amplifier, 10 A peak, 5 A continuous; x4096 MXU<sup>(1)</sup>

/3-ML10MI Linear amplifier, 10 A peak, 5 A continuous; x4096 MXU<sup>(1)</sup> with I/O option /3-ML10H Digital linear amplifier, 10 A peak, 5 A continuous; x65536 MXH<sup>(1)</sup>

Digital linear amplifier, 10 A peak, 5 A continuous; x65536 MXH<sup>(1)</sup> with I/O option /3-ML10HI

Note:

#### Axis 4 Amplifier Options

/4-MP10 Digital PWM amplifier, 10 A peak, 5 A continuous

/4-MP10I Digital PWM amplifier, 10 A peak, 5 A continuous with I/O option /4-MP10M Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU<sup>(1)</sup>

/4-MP10MI Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU(1) and I/O option

Digital PWM amplifier, 10 A peak, 5 A continuous with half bus option /4-MP10-HB /4-MP10I-HB Digital PWM amplifier, 10 A peak, 5 A continuous with I/O and half bus option /4-MP10M-HB Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU<sup>(1)</sup> and half bus option

/4-MP10MI-HB Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU<sup>(1)</sup> with I/O and half bus option

/4-ML10 Linear amplifier, 10 A peak, 5 A continuous

/4-ML10I Linear amplifier, 10 A peak, 5 A continuous with I/O option /4-ML10M Linear amplifier, 10 A peak, 5 A continuous; x4096 MXU<sup>(1)</sup>

Linear amplifier, 10 A peak, 5 A continuous; x4096 MXU  $^{\!\scriptscriptstyle (1)}$  with I/O option /4-ML10MI

/4-ML10H Digital linear amplifier, 10 A peak, 5 A continuous; x65536 MXH<sup>(1)</sup>

/4-ML10HI Digital linear amplifier, 10 A peak, 5 A continuous; x65536 MXH<sup>(1)</sup> with I/O option

#### Axis 5 Amplifier Options

/5-MP10 Digital PWM amplifier, 10 A peak, 5 A continuous /5-MP10I

Digital PWM amplifier, 10 A peak, 5 A continuous with I/O option /5-MP10M Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU<sup>(1)</sup>

Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU(1) and I/O option /5-MP10MI

Digital PWM amplifier, 10 A peak, 5 A continuous with half bus option /5-MP10-HB Digital PWM amplifier, 10 A peak, 5 A continuous with I/O and half bus option /5-MP10I-HB /5-MP10M-HB Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU<sup>(1)</sup> and half bus option /5-MP10MI-HB Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU<sup>(1)</sup> with I/O and half bus option

#### Axis 6 Amplifier Options

/6-MP10 Digital PWM amplifier, 10 A peak, 5 A continuous

/6-MP10I Digital PWM amplifier, 10 A peak, 5 A continuous with I/O option /6-MP10M Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU<sup>(1)</sup>

/6-MP10MI Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU<sup>(1)</sup> with I/O option

/6-MP10-HB Digital PWM amplifier, 10 A peak, 5 A continuous with half bus option Digital PWM amplifier, 10 A peak, 5 A continuous with I/O and half bus option /6-MP10I-HB /6-MP10M-HB Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU<sup>(1)</sup> and half bus option Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU(1) with I/O and half bus option /6-MP10MI-HB

<sup>1.</sup> Effective multiplication factor specified after quadrature decoding (if applicable).

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# $\textbf{Npaq}^{\text{0}} \ \textbf{MR} \ \textbf{Series} \ \textbf{ORDERING} \ \textbf{INFORMATION}$

#### **Axis 7 Amplifier Options**

/7-MP10	Digital PWM amplifier, 10 A peak, 5 A continuous
/7-MP10I	Digital PWM amplifier, 10 A peak, 5 A continuous with I/O option
/7-MP10M	Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU <sup>(1)</sup>
/7-MP10MI	Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU <sup>(1)</sup> and I/O option
/7-MP10-HB	Digital PWM amplifier, 10 A peak, 5 A continuous with half bus option
/7-MP10I-HB	Digital PWM amplifier, 10 A peak, 5 A continuous with I/O and half bus option
/7-MP10M-HB	Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU <sup>(1)</sup> and half bus option
/7-MP10MI-HB	Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU <sup>(1)</sup> with I/O and half bus option

Note: 1. Effective multiplication factor specified after quadrature decoding (if applicable).

#### **Axis 8 Amplifier Options**

/8-MP10	Digital PWM amplifier, 10 A peak, 5 A continuous
/8-MP10I	Digital PWM amplifier, 10 A peak, 5 A continuous with I/O option
/8-MP10M	Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU <sup>(1)</sup>
/8-MP10MI	Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU(1) and I/O option
/8-MP10-HB	Digital PWM amplifier, 10 A peak, 5 A continuous with half bus option
/8-MP10I-HB	Digital PWM amplifier, 10 A peak, 5 A continuous with I/O and half bus option
/8-MP10M-HB	Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU <sup>(1)</sup> and half bus option
/8-MP10MI-HB	Digital PWM amplifier, 10 A peak, 5 A continuous; x4096 MXU <sup>(1)</sup> with I/O and half bus option

Note: 1. Effective multiplication factor specified after quadrature decoding (if applicable).

### Line Cord (must select one)

/ENGLAND	UK compatible line cord
/GERMANY	German compatible line cord
/ISRAEL	Israel compatible line cord
/INDIA	India compatible line cord
/AUSTRALIA	Australia compatible line cord
/US-115VAC	US 115 VAC line cord
/US-230VAC	US 230 VAC line cord
/NO LINECORD	M- 1:

No line cord /NO-LINECORD

### Brake Options (up to 4 selections allowable)

/BRAKE-1	Axis 1 wired for 24 V, 1 A brake	
/BRAKE-2	Axis 2 wired for 24 V, 1 A brake (amp must have "I" or "MI" option)	
/BRAKE-3	Axis 3 wired for 24 V, 1 A brake (amp must have "I" or "MI" option)	
/BRAKE-4	Axis 4 wired for 24 V, 1 A brake (amp must have "I" or "MI" option)	
/BRAKE-5	Axis 5 wired for 24 V, 1 A brake (amp must have "I" or "MI" option)	
/BRAKE-6	Axis 6 wired for 24 V, 1 A brake (amp must have "I" or "MI" option)	
/BRAKE-7	Axis 7 wired for 24 V, 1 A brake (amp must have "I" or "MI" option)	
/BRAKE-8	Axis 8 wired for 24 V, 1 A brake (amp must have "I" or "MI" option)	

#### Options (multiple selections allowable)

-ESTOP1	Controller stops motion, then disables servo control. Internal positive guided relay with monitor contact disconnects AC power source from motor. Operator risk assessment is the responsibility of the end user or integrator.
-ESTOP2	Same as ESTOP1 but uses two relays
-ESTOP3	Same as ESTOP2 but contains 1 second bus discharge resistors
-SLIDE	Rack-mount slides

#### Integration (Required)

Aerotech offers both standard and custom integration services to help you get your system fully operational as quickly as possible. The following standard integration options are available for this system. Please consult Aerotech if you are unsure what level of integration is required, or if you desire custom integration support with your system.

-TAS Integration - Test as system

> Testing, integration, and documentation of a group of components as a complete system that will be used together (ex: drive, controller, and stage). This includes parameter file generation, system

tuning, and documentation of the system configuration.

-TAC Integration - Test as components

> Testing and integration of individual items as discrete components that ship together. This is typically used for spare parts, replacement parts, or items that will not be used together. These

components may or may not be part of a larger system.