# Ndrive Series Digital Servo Amplifiers – PWM

Wide output power range from 10 A peak to 200 A peak at 320 VDC

2- or 3-phase AC line input or DC input

CE approved and NRTL safety certification; follows the 2011/65/EU RoHS 2 Directive

## **PWM power stages**

Digital current, velocity, and position loops for improved motion stability

Optional integrated encoder multiplier for higher throughput and reduced wiring

Flexible design provides ability to drive brushless and DC brush-type servomotors as well as stepping motors

**Encoder or resolver feedback** 

## New Designs Available!

We recommend the XC4e (in place of the Ndrive HPe) and the XC4 (in place of the Ndrive CP) for all new applications.

The Ndrive<sup>®</sup> family of digital servo amplifiers are high performance discrete drives used with the Automation 3200 motion controller. These drives are capable of controlling brushless, DC brush, and stepper motors over a wide range of operating voltages and currents. Based on a common architecture, Ndrive amplifiers perform both current- and position-loop closures digitally.

The use of high-performance double-precision processors allows these drives to generate ultra-smooth motion profiles. Servo system response is optimized with the use of up to eight second-order loop-shaping filters, precise timealigned feed-forward and other proprietary techniques with loop closure rates up to 20 kHz.

The Ndrive family is offered in a number of highly efficient PWM versions. The Ndrive MP is a low power, small







Ndrive HPe

Ndrive CP

Ndrive MP

footprint PWM drive ideal for space-sensitive applications. The Ndrive CP is a medium-power PWM drive capable of running directly from AC mains voltage and is optimized for cost-sensitive applications. The Ndrive HPe is the highest performance PWM drive providing a host of features not available on the other PWM drives, and is available in output current ranges from 10 A to 200 A peak.

Options for the Ndrive family include integral encoder interpolation, one- to three-axis position synchronized output (PSO), automatic brake control, digital and analog I/O expansion, absolute encoder interface, and one- or twochannel resolver interfaces. An optional dedicated ethernet port is available on the HPe drives for connection to thirdparty I/O expansion devices. This provides the potential to connect to a large number of I/O points typically required for PLC-type applications.

Any combination of Ndrive amplifiers may be connected to the Automation 3200 FireWire® network, allowing the system to be customized as needed.

### **Ndrive Series COMPARISON**



Ndrive HPe Width: 99 mm Height: 232.4 mm



Ndrive CP Width: 63.5 mm Height: 198.2 mm



Ndrive MP Width: 41.1 mm Height: 141.2 mm

Ndrive Comparison Chart	Ndrive HPe	Ndrive CP	Ndrive MP
PC Interface	FireWire₀	FireWire <sub>®</sub>	FireWire₀
Current Output, Peak(1)	150-200 A	10-30 A	10 A
Current Output, Continuous(1)	5-75 A	5-10 A	5 A
Bus Voltage	±10-320 VDC	±10-320 VDC	±40 VDC
Amplifier Type	PWM	PWM	PWM
Motor Supply Voltage	2 or 3 Phase AC	2 Phase AC	DC
Standard I/O <sub>(2)</sub>	4-DO/6-DI 1-AO/1-AI	4-DO/6-DI 1-AO/1-AI	1-AI
Expansion I/O <sub>(2)</sub> (Additional to Base I/O)	16-DO/16-DI 3-AO/3-AI	16-DO/16-DI 1-AO/1-AI	8-DO/8-DI 1-AO/1-AI
Single Axis PSO <sub>(3)</sub>	Yes	Yes	Yes
Dual Axis PSO <sub>(3)</sub>	Yes	No	No
Triple Axis PSO <sub>(3)</sub>	Yes	No	No
Ethernet Capable for Third-Party I/O	Yes	No	No

Notes:

Peak value of the sine wave; rms current for AC motors is 0.707 \* A<sup>ak</sup>.
 D0 = Digital Output; DI = Digital Input; AO = Analog Output; AI = Analog Input.
 PSO not available on Ndrive CP/MP when using integral MXU.

## **Ndrive HPe Series SPECIFICATIONS**

Ndrive HPe	Units	10	20	30	50	75	100	150	200
Motor Style		Brush, Brushless, Stepper <sup>(1)</sup>							
Motor Supply	VAC	Single-Phase 7-240 V; 50/60 Hz         Single- or Three-Phase 115 or 230 V; 50/60 Hz						/60 Hz	
Control Supply <sup>(2)</sup>	VAC	85-240 VAC; 50/60 Hz							
Bus Voltage <sup>(3)</sup>	VDC	10-320(3)							
Peak Output Current (1 sec) <sup>(4)</sup>	A <sub>pk</sub>	10 20 30 50 75 100 150					200		
Continuous Output Current <sup>(4)</sup>	A <sub>pk</sub>	5	10	10	25	37	50	75	75
Digital Inputs		6 Optically-Isolated (2 High Speed)							
Digital Outputs		4 Optically-Isolated							
Analog Inputs		One 16-bit Differential; ±10 V							
Analog Outputs		One 16-bit Single-Ended; ±10 V							
Dedicated Axis I/O on Feedback Connector		Three Limit Inputs (CW, CCW, Home); Three Hall Effect Inputs (A, B, C); Three High-Speed differential Inputs (sin, cos, mkr for encoder); Motor Over-Temperature Input							
Dedicated I/O on Auxiliary Feedback Connector		sin, cos, mkr for Aux Enc; Aux Enc can be used for PSO Output							
I/O Expansion Board <sup>(5)</sup>		16/16 Digital Opto-Isolated; 3 Analog In (±10 V, 16-bit Differential); 3 Analog Out (±10 V, 16-bit)							
High Speed Data Capture		Yes (50 ns Latency)							
Automatic Brake Control					Standard;	24 V at 1 A			
Emergency Stop Sense Input (ESTOP) <sup>(6)</sup>				St	andard; 24 \	/ Opto-Isolat	ed		
Position Synchronized Output (PSO)				Single Axis	Standard, T	wo/Three A	kis Optional		
Can Output Multiplied Encoder					Y	es			
Can Output Square Wave Encoder					Y	es			
Primary Encoder Input Frequency		500 kHz	Amplified Si	ne Wave St	andard (for c	nboard mult	iplier); 40 Mł	Hz TTL Squ	are Wave
Secondary Encoder Input Frequency					32 MHz Sc	uare Wave			
Encoder Multiplication				Up to x65	536 with Qua	adrature Out	put (MXH)		
Absolute Encoder				Renishaw I	Resolute BiS	S; EnDat 2.1	; EnDat 2.2		
Resolver Interface		Optional; 1 or 2 Channel; 16-bit							
Internal Shunt Resistor		40 W Continuous; 440 W Continuous 400 W Peak (5 seconds)							
External Shunt		Optional							
Ethernet		Optional							
USB					Ν	lo			
RS-232					Ν	lo			
FireWire					Y	es			
Fieldbus					Modbus T	CP on PC			
Current Loop Update Rate	kHz				2	0			
Servo Loop Update Rate	kHz				1	3			
Power Amplifier Bandwidth	kHz			S	electable Thr	ough Softwa	are		
Minimum Load Inductance	mH			0.1 @	160 VDC (1	.0 mH @ 320	OVDC)		
Operating Temperature	°C				0 to	50			
Storage Temperature	°C	-30 to 85							
Weight	kg (lb)	) 2.36 (5.2) 6.64 (14.6) 11.06 (24.4)					õ (24.4)		
Standards		CE approved, NRTL safety certification, EU 2015/863 RoHS 3 directive							
Notes:									

Notes: 1. For stepper motors only, one-half of bus voltage is applied across the motor (e.g., 80 VDC supply results in 40 VDC across stepper motor). 2. "Keep Alive" supply. 3. Output voltage dependent upon input voltage. 4. Peak value of the sine wave; rms current for AC motors is 0.707 \* Apk. 5. Requires IO option. 6. Requires output relay to remove motor supply power.

6. Requires external relay to remove motor supply power.

Ndrive<sup>®</sup> PWM Amplifiers/Drives

## **Ndrive CP Series SPECIFICATIONS**

Ndrive CP	Units	10	20	30		
Motor Style		Brush, Brushless, Stepper(1)				
Motor Supply	VAC	Single-Phase 7-240 VAC; 50/60 Hz				
Control Supply <sub>(2)</sub>	VAC	85-240 VAC; 50/60 Hz				
Bus Voltage <sub>(3)</sub>	VDC	10-320 <sub>(3)</sub>				
Peak Output Current (1 sec)(4)	A <sub>pk</sub>	10	20	30		
Continuous Output Current <sub>(4)</sub>	A <sub>pk</sub>	5	10	10		
Digital Inputs	<u> </u>	6 Optically-Isolated (2 High Speed)				
Digital Outputs	<u> </u>	4 Optically-Isolated				
Analog Inputs	]	One 16-bit Differential; ±10 V				
Analog Outputs	—	One 16-bit Single-Ended; ±10 V				
Dedicated Axis I/O on Feedback Connector		Three Limit Inputs (CW, CCW, Home); Three Hall Effect Inputs (A, B, C); Three High-Speed differential Inputs (sin, cos, mkr for encoder); Motor Over-Temperature Input				
Dedicated I/O on Auxiliary Feedback Connector		sin, cos, mkr for Aux Enc; Aux Enc can be used for PSO Output				
I/O Expansion Board <sub>(5)</sub>		16/16 Digital Opto-Isolated; 1 Analog In (±10 V, 12-bit Differential); 1 Analog Out (±10 V, 16-bit)				
High Speed Data Capture		Yes (50 ns Latency)				
Automatic Brake Control	<u> </u>		Standard; 24 V at 1 A			
Emergency Stop Sense Input (ESTOP)(6)	<u> </u>		Standard; 24 V Opto-Isolated			
Position Synchronized Output (PSO)	—		Single Axis Only			
Can Output Multiplied Encoder			No			
Can Output Square Wave Encoder			Yes			
Primary Encoder Input Frequency		200 kHz Amplified Sine Way	e Standard (for onboard multiplier)	; 40 MHz TTL Square Wave		
Secondary Encoder Input Frequency			40 MHz Square Wave			
Encoder Multiplication	—		Up to x4096 (MXU)			
Absolute Encoder		Renist	naw Resolute BiSS; EnDat 2.1; EnI	Dat 2.2		
Resolver Interface	—	N/A				
Internal Shunt Resistor		40 W Continuous; 400 W Peak (5 seconds)				
External Shunt		Optional				
Ethernet	—	N/A				
USB		No				
RS-232			No			
FireWire			Yes			
Fieldbus			Modbus on PC			
Current Loop Update Rate	kHz		20			
Servo Loop Update Rate	kHz		8			
Power Amplifier Bandwidth	kHz		Selectable Through Software			
Minimum Load Inductance	mH	0.	1 @ 160 VDC (1.0 mH @ 320 VD	C)		
Operating Temperature	°C		0 to 50			
Storage Temperature	°C	-30 to 85				
Weight	kg (lb)	1.64 (3.6)				
Standards		CE approved, NRTL safety certification, EU 2015/863 RoHS 3 directive				

Notes:

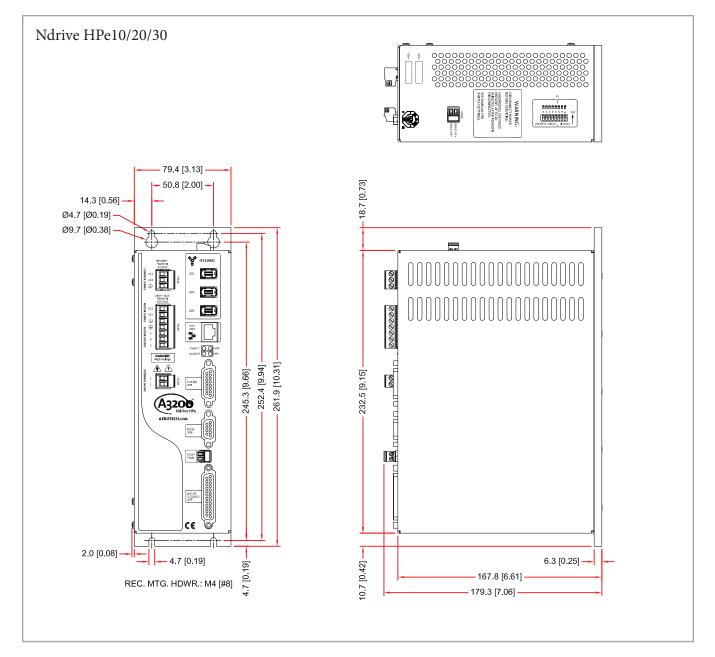
Notes: 1. For stepper motors only, one-half of bus voltage is applied across the motor (e.g., 80 VDC supply results in 40 VDC across stepper motor). 2. "Keep Alive" supply. 3. Output voltage dependent upon input voltage. 4. Peak value of the sine wave; rms current for AC motors is 0.707 \* A<sup>pk</sup>. 5. Requires IO option. 6. Requires external relay to remove motor supply power.

## **Ndrive MP Series SPECIFICATIONS**

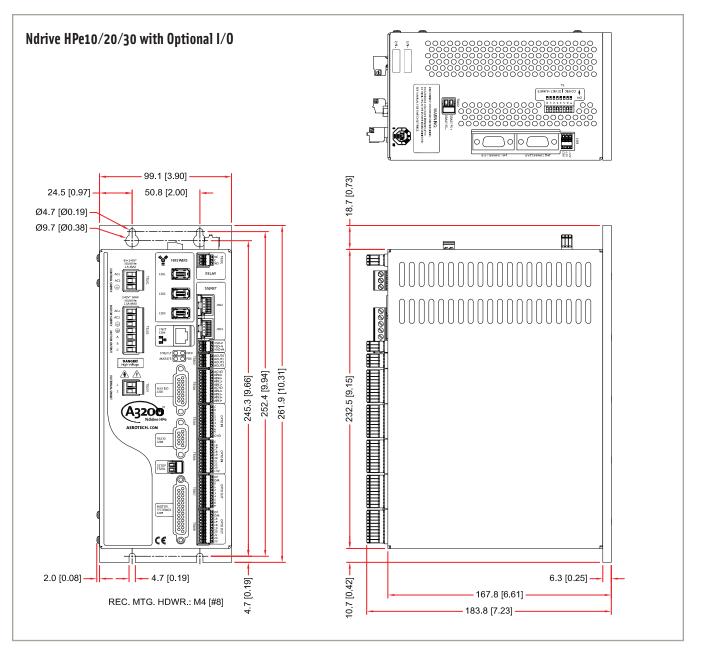
Motor Style         VDC           Motor Supply         VDC           Control Supply <sub>(2)</sub> VDC           Bus Voltage <sub>(3)</sub> VDC           Peak Output Current (1 sec) <sub>(4)</sub> A <sub>pk</sub> Continuous Output Current <sub>(4)</sub> A <sub>pk</sub> Digital Inputs         —           Digital Outputs         —	Brush, Brushless, Stepper(1)           10-80           24-80           10-80           10           5           N/A           One 12-bit Differential; ±10 V           N/A
Control Supply(2)         VDC           Bus Voltage(3)         VDC           Peak Output Current (1 sec)(4)         Apple           Continuous Output Current(4)         Apple           Digital Inputs            Digital Outputs	24-80 10-80 10 5 N/A N/A One 12-bit Differential; ±10 V N/A
Bus Voltage(3)         VDC           Peak Output Current (1 sec)(4)         Apple           Continuous Output Current(4)         Apple           Digital Inputs            Digital Outputs	10-80         10         5         N/A         N/A         One 12-bit Differential; ±10 V         N/A
Peak Output Current (1 sec) <sub>(4)</sub> A <sub>pk</sub> Continuous Output Current <sub>(4)</sub> A <sub>pk</sub> Digital Inputs         —           Digital Outputs         —	10 5 N/A N/A One 12-bit Differential; ±10 V N/A
Continuous Output Current <sub>(4)</sub> A <sub>pk</sub> Digital Inputs     —       Digital Outputs     —	5 N/A N/A One 12-bit Differential; ±10 V N/A
Digital Inputs     —       Digital Outputs     —	N/A N/A One 12-bit Differential; ±10 V N/A
Digital Inputs     —       Digital Outputs     —	N/A One 12-bit Differential; ±10 V N/A
	One 12-bit Differential; ±10 V N/A
	N/A
Analog Inputs –	
Analog Outputs	
Dedicated Axis I/O on Feedback Connector	Three Limit Inputs (CW, CCW, Home); Three Hall Effect Inputs (A, B, C); Three High-Speed differential Inputs (sin, cos, mkr for encoder); Motor Over-Temperature Input
Dedicated I/O on Auxiliary Feedback Connector	N/A
I/O Expansion Board —	8/8 Digital Opto-Isolated; 1 Analog In (±10 V, 12-bit Differential); 1 Analog Out (±5 V, 16-bit); sin, cos, mrk for Aux Enc; Aux Enc can be used for PSO Output
High Speed Data Capture	Yes (50 ns Latency)
Automatic Brake Control —	Optional <sub>(6)</sub>
Emergency Stop Sense Input (ESTOP) <sub>(6)</sub> —	Standard; 24 V Opto-Isolated
Position Synchronized Output (PSO) —	Optional <sub>(5)</sub>
Can Output Multiplied Encoder	No
Can Output Square Wave Encoder	No
Primary Encoder Input Frequency	200 kHz Amplified Sine Wave Standard (for onboard multiplier); 40 MHz TTL Square Wave
Secondary Encoder Input Frequency	32 MHz Square Wave
Encoder Multiplication —	Up to x1024 (MXU)
Resolver Interface —	N/A
Internal Shunt Resistor	N/A
External Shunt	N/A
Ethernet —	N/A
USB	No
RS-232	No
FireWire	Yes
Fieldbus	Modbus TCP on PC
Current Loop Update Rate kHz	20
Servo Loop Update Rate kHz	8
Power Amplifier Bandwidth kHz	Selectable Through Software
Minimum Load Inductance mH	0.1 @ 80 VDC
Operating Temperature °C	0 to 50
Storage Temperature °C	-30 to 85
Weight kg (lb)	0.45 (1.0)
Standards	CE approved, NRTL safety certification, EU 2015/863 RoHS 3 directive

Notes:
1. For stepper motors only, one-half of bus voltage is applied across the motor (e.g., 80 VDC supply results in 40 VDC across stepper motor).
2. "Keep Alive" supply.
3. Output voltage dependent upon input voltage.
4. Peak value of the sine wave; rms current for AC motors is 0.707 \* A<sup>ak</sup>.
5. Requires IO option.
6. Requires external relay to remove motor supply power.

## Ndrive HPe10/20/30 DIMENSIONS

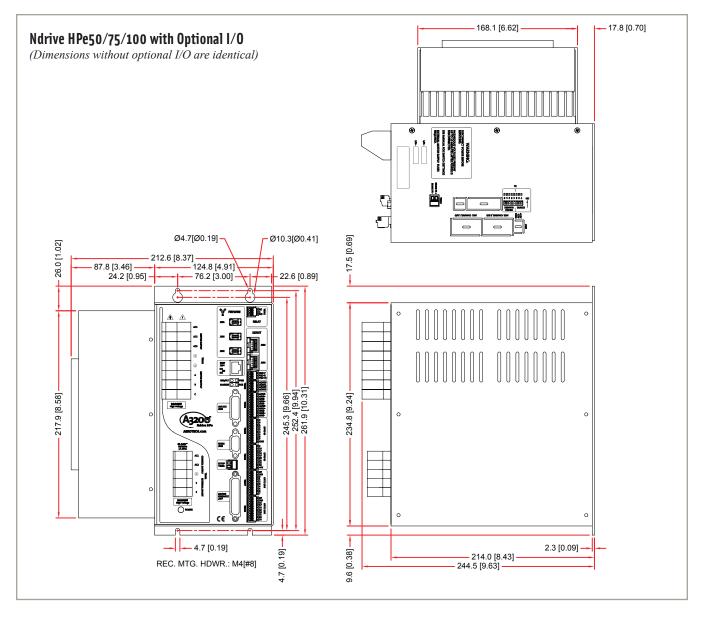


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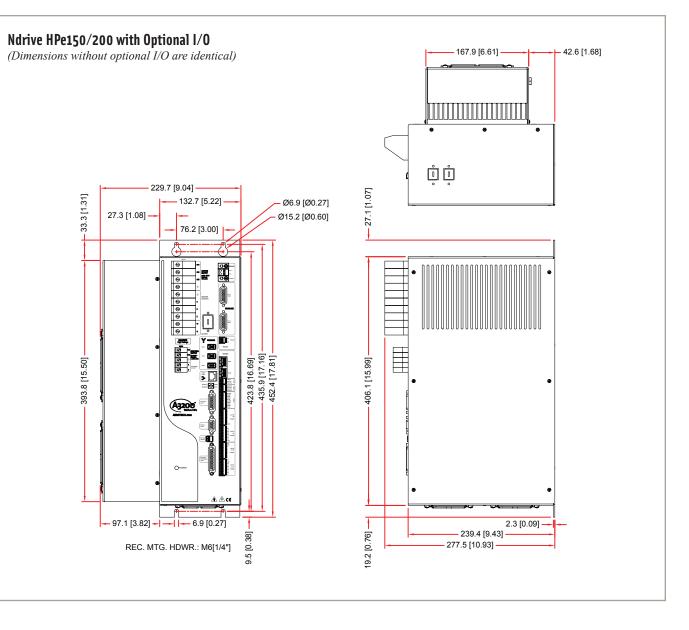


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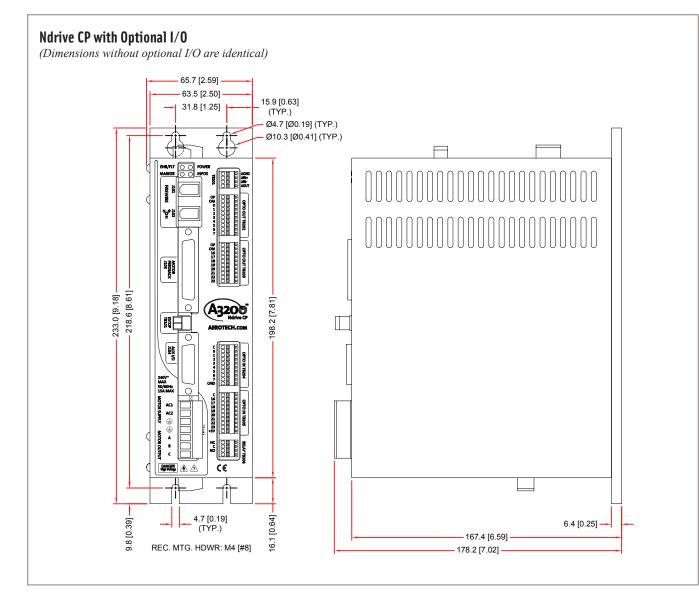
#### Ndrive HPe50/75/100 DIMENSIONS



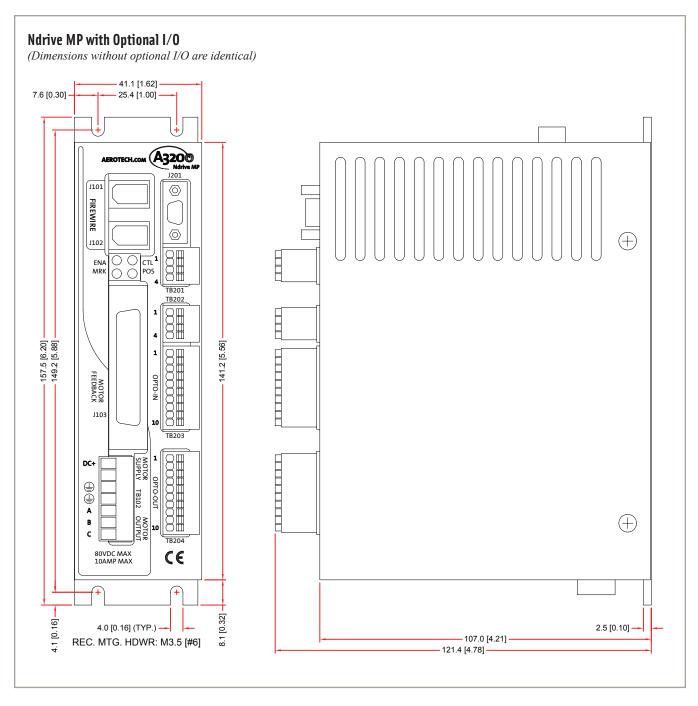
### Ndrive HPe150/200 DIMENSIONS



### **Ndrive CP DIMENSIONS**



#### **Ndrive MP DIMENSIONS**



#### **Ndrive Ordering Information**

Visit Aerotech's website for complete ordering information.