

AEROTECH AUTOMATION1



Compact PWM+ Servo Drive with Motion Controller **Automation1 iXC2e**

Compact PWM+ Drive & Motion Controller

The Automation1 iXC2e servo motor drive combines PWM+ technology with the Automation1 motion controller's full capabilities, improving motion quality with sub-nanometer in-position stability and boosting throughput with fast step-and-settle and superior tracking performance—all in our smallest panel-mount drive.

The integrated Automation1-iSMC controller enables expert-level tuning through intuitive tools, tight coordination with other Automation1 drives over HyperWire and integration with automation systems over EtherCAT, EtherNet/IP™, Modbus TCP/IP or TCP Socket interfaces.

Synchronize laser firing or process triggers with motion using multi-axis PSO, precisely align digital and analog I/O samples with the servo loop and prevent unexpected motion with safe torque off (STO).

Automation1

The iXC2e is a part of the user-friendly Automation1 motion control platform, which includes the following:

- ◆ **Development Software**
- ◆ **Controls**
- ◆ **Motor Drives**
- ◆ **Fiber-Optic HyperWire® Communication Bus**

KEY FEATURES:

- ◆ Unlocks the full **MOTION CONTROL** power of our Automation1-iSMC intelligent software-based motion controller
- ◆ Features **COMPLETE CONFIGURATION & PERFORMANCE** capability of the XC2e PWM servo drive
- ◆ Includes local drive with **100 VDC BUS** motor power & up to **10 AMPS PEAK** output
- ◆ **CONNECT TO THE CONTROLLER** using **EtherNet/IP™** | **EtherCAT®** Modbus TCP/IP or TCP Socket interface
- ◆ Allows for up to **12 AXES OF CONTROL** when more Automation1 drives are connected over the HyperWire fiber-optic bus
- ◆ Includes PSO, the **ULTIMATE IN POSITION-BASED CONTROL** for industrial lasers, cameras & more
- ◆ Includes **SAFE TORQUE OFF (STO)** functional safety

AUTOMATION1 iXC2e GENERAL SPECIFICATIONS

| CATEGORY | SPECIFICATION |
|--|---|
| Motion Controller⁽¹⁾ | Aerotech's Automation1-iSMC Intelligent Software-Based Motion Controller (version 2.2 and above) |
| Motor Style | Brush, brushless, voice coil, stepper ⁽²⁾ |
| Control Supply | 24 VDC |
| Motor Supply | 15-100 VDC |
| Bus Voltage⁽³⁾ | 15-100 VDC |
| PWM Frequency | 20 kHz |
| Peak Output Current (1 sec)⁽⁴⁾ | 10 A _{pk} |
| Continuous Output Current^(4c) | 5 A |
| Position Synchronized Output (PSO) | <p>Standard: One-axis PSO (includes one-axis Part-Speed PSO)*</p> <p>Optional: Two-axis PSO (includes two-axis Part-Speed PSO)* Two-axis Part-Speed PSO only* Three-axis Part-Speed PSO only*</p> <p>*Requires adding an expansion board to the drive to output PSO pulses via a physical connection.</p> |
| 25-Pin Motor Feedback Connector | <p>High-speed differential inputs (encoder sin, cos & marker) CW and CCW limits Hall effect sensor inputs (A, B & C) Analog motor temperature input (accepts digital) Brake output</p> |
| Multiplier Options | <p>MX0 option: Primary encoder: 40 million counts per second square-wave input Auxiliary encoder: 40 million counts per second square-wave input</p> <p>MX2 option: Primary encoder: 2 MHz/450 kHz (bandwidth selectable) sine-wave input, encoder multiplier up to 65,536 Auxiliary encoder: 40 million counts per second square-wave input</p> <p>MX3 option: Primary encoder: 2 MHz/450 kHz (bandwidth selectable) sine-wave input, encoder multiplier up to 65,536 Auxiliary encoder: 200 kHz sine-wave input, encoder multiplier up to x16,384*</p> <p>*Encoders multiplied with this input cannot be echoed out</p> |
| I/O Expansion Board (-EB1) | <p>PSO output connector with up to 12.5 MHz output rate Auxiliary Encoder Port 1x 16-bit differential, ±10 V analog input 1x 16-bit single-ended, ±10 V analog output 8x optically isolated digital inputs 8x optically isolated digital outputs</p> |

Chart continued on next page

AUTOMATION1 iXC2e GENERAL SPECIFICATIONS

| CATEGORY | SPECIFICATION |
|-----------------------------------|--|
| I/O Expansion Board (-EB2) | PSO output connector with up to 12.5 MHz output rate Auxiliary Encoder Port 2x Industrial Ethernet Ports |
| Drive Array Memory | 67.1 MB (16,777,216 32-bit elements) |
| High Speed Data Capture | Yes (50 ns latency) |
| Safe Torque Off (STO) | Yes (SIL3/PLe/Cat 4) |
| HyperWire Connections | 1x HyperWire small form-factor pluggable (SFP) port |
| Automatic Brake Control | Standard (24 V at 0.5 A) |
| Absolute Encoder | Renishaw Resolute BiSS; EnDat 2.1; EnDat 2.2, and SSI |
| Current Loop Update Rate | 20 kHz |
| Servo Loop Update Rate | 20 kHz |
| Power Amplifier Bandwidth | 2500 Hz maximum (software selectable) |
| Power Amplifier Efficiency | 85-95% ⁽⁵⁾ |
| Minimum Load Inductance | 0.1 mH |
| Operating Temperature | 0 to 40 °C |
| Storage Temperature | -30 to 85 °C |
| Weight | 0.54 kg (1.20 lb.) |
| Compliance | CE approved, NRTL safety certification, EU 2015/863 RoHS 3 directive |

1. See the [Automation1-iSMC](#) controller page for more information.
2. For stepper motors only, one-half of bus voltage is applied across the motor (e.g., 80 VDC supply results in 40 VDC across stepper motor).
3. Output voltage dependent upon input voltage.
4. Peak value of the sine wave; RMS current for AC motors is $0.707 A_{pk}$.
5. Dependent on total output power: efficiency increases with increasing output power.



AUTOMATION1 iXC2e ORDERING OPTIONS

Automation1-iXC2e

Automation1-iXC2e Automation1-iXC2e - Enhanced, Compact PWM Servo Drive with Motion Controller

Peak Current

-10 10 A peak, 5 A cont. current (default)

Amplifier Type

-PWM+ With PWM+ amplifier

Expansion Board

-EB0 No expansion board (default)
-EB1 Expansion board with analog/digital I/O
-EB2 Expansion board with industrial Ethernet ports

Multiplier

-MX0 No encoder multiplier (default)
-MX2 x65536 multiplier (primary), no multiplier (auxiliary)
-MX3 x65536 multiplier (primary), x16384 multiplier (auxiliary)

PSO⁽¹⁾

-PSO1 One-axis PSO (includes one-axis Part-Speed PSO) (default)
-PSO2 Two-axis PSO (includes three-axis Part-Speed PSO)
-PSO5 Two-axis Part-Speed PSO
-PSO6 Three-axis Part-Speed PSO

1. PSO functionality is included in the base iXC2e. The -EB1 board is required to use PSO logic to generate an output signal.

AUTOMATION1 PS2 DIN RAIL POWER SUPPLY ORDERING OPTIONS

Automation1-PS2

Automation1 PS2 Automation1-PS2 - Din-rail mounted power supply for 1 to 4 compact servo drives

Drive Type (Required)

-D1 PS2 for XC2, XC2e drives & iXC2e, iXC2 drive-based controllers
-D2 PS2 for XL2e drives & iXL2e drive-based controllers

Power Output (Required)

-P1 240 watts at 24 VDC
-P2 240 watts at 48 VDC
-P3 480 watts at 48 VDC
-P4 480 watts at 96 VDC
-P5 240 watts at +/-12 VDC (10A)
-P6 240 watts at +/-24 VDC (5A)
-P7 480 watts at +/-48 VDC (5A)

Number of Axes (Required)

-AX01 1 axis of wiring
-AX02 2 axes of wiring
-AX03 3 axes of wiring
-AX04 4 axes of wiring

AUTOMATION1 iXC2e DIMENSIONS

AUTOMATION1 iXC2e, -EB0 OPTION



